**18/01/2019**

**Assignment 3-Lego Robot**

Team E5

Andrew Payne

Julia Derebecka

Seshan Kanagasabai

For our assignment, all team members were present for the initial stages. This included the planning and testing of each of the sensors we used, and the first stage of the assignment which was to make the robot find the black line and turn

Due to exceptional circumstances Seshan was not present for the rest of the assignment. Julia and Andrew developed the main body of the program, planning how to navigate the rest of the course and debugging problems along the way.

Andrew organised the methods into separate elements for the core of the program, and Julia developed the main algorithms to implement these methods making the robot move around the course.

Both Andrew and Julia tested the final parts for timings and speeds off the back of this.